EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1	10/767193	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/07 06:38
S2	2951	(robot or android or machine) and (arm or limb or appendage)and (hold or grasp or clutch or grip or clasp) and (proximal) and (distal) and (visual or ccd or camera or optical)and (orientation or bearing or direction or coordination or position)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 16:04
S3	1908	(700/245,259).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/02/05 15:59
S4	3113	((700/245,259,250) or (382/153) or (623/60,61,64) or (294/86+) or (414/589+,591,730+,744.1+,749.1, 754+)).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/02/05 15:36
S5	42	S2 and S3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 15:59
S6	50	S2 and S4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 15:59

S7	986	(robot or android or machine) and (arm or limb or appendage)and (hold or grasp or clutch or grip or clasp) and (proximal) and (distal) and (visual or ccd or camera or optical)and (orientation or bearing or direction or coordination or position) and (container)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 16:11
S8	9	S6 and container	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 16:08
S9	210	(robot or android or machine) same (arm or limb or appendage)same (hold or grasp or clutch or grip or clasp) same (visual or ccd or camera or optical)same (orientation or bearing or direction or coordination or position) and (container)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 16:37
S10	69	(robot or android or machine) same (arm or limb or appendage)same (hold or grasp or clutch or grip or clasp) same (visual or ccd or camera or optical)same (orientation or bearing or direction or coordination or position) same (container)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 16:14
S11	1092	(robot or android or machine) same (arm or limb or appendage)same (hold or grasp or clutch or grip or clasp) same (visual or ccd or camera or optical)same (orientation or bearing or direction or coordination or position) and hand	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/05 16:42
S12	24	("3804270" | "4017721" | "4169758" | "4305130" | "4402053" | "4412293" | "4613269" | "4613942" | "4634947" | "4674057" | "4680802" | "4704694" | "4731856" | "4821206").PN. OR ("4985846").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/05 16:43
S13	38	("3804270" | "4017721" | "4146924" | "4305130" | "4344146" | "4402053" | "4412293" | "4443855" | "4486842" | "4539703").PN. OR ("4613269"). URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/05 16:45

S14	31	("3804270" | "3888362" | "3986007" | "4017721" | "4146924" | "4187051").PN. OR ("4412293"). URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/05 16:46
S15	25	("4412293").URPN.	USPAT	OR	ON	2007/02/05 16:47
S16	10	("4146924" | "4412293" | "5023426" | "5233152" | "5446835" | "5579415" | "6141863" | "6301763" | "6592315" | "6763284").PN. OR ("7123992"). URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/05 16:49
S25	26	robot and arm and hand and orientation and command and controller and axis and hold and rotation and (visual or ccd or camera) and (overlapping or random or jumbled) and slide and change and distal and proximal	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/06 06:35
S26	0	EP1256860a2	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/06 16:16
S27	0	"US6597971 B2"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/06 16:25
S28	2	"6597971 B2"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/06 16:26
S29	0	"2002169522 A1"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/06 16:26

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S30	2	"2002169522"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/06 16:26
S31	7	("4338672" | "4975856" | "5837960" | "5917726" | "6415191").PN. OR ("6597971"). URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/06 16:33
S33	2	"20040186624"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/07 06:40
S34	14	robot with objects same visual same sensor same taught	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/07 06:47
S36	37	masaru near oda and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/07 06:48
S37	1	"4402053".PN.	USPAT; USOCR	OR	ON	2007/02/08 07:05